Improved Regret Bounds of (Multinomial) Logistic **Bandits via Regret-to-Confidence-Set Conversion**

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Optimization and







The Plan for Today

- Logistic Bandits 101
- Improved Regrets for Logistic Bandits
- Conclusion and Future Works

• New confidence set for logistic bandits via (online) regret-to-confidence-set (**O2CS**)

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We propose a framework in which one can construct a confidence set using an achievable online learning regret bound (without ever running the alg), and apply it to improve the regret bounds of (multinomial) logistic bandits.

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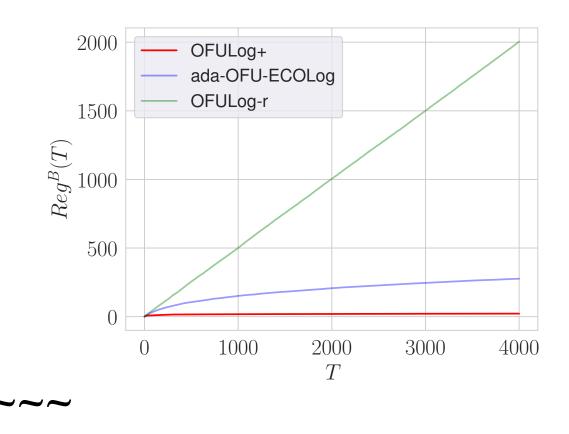


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Logistic Bandits 101 Motivation

- Useful in modeling exploration-exploitation dilemma with *binary/discrete-valued* rewards and items' feature vectors
 - e.g., news recommendation ('click', 'no click'), online ad placement ('click', 'show me later', 'never show again', 'no click')
- Naive reduction to linear bandits is quite suboptimal[Li et al., WWW'10; ICMLW'11]!



The Web Conference 2023 - Seoul Test of Time Award (presented at The Web Conference 2023 in Austin)

Winners: Wei Chu, Lihong Li, John Langford and Robert Schapire for their paper "A Contextual-Bandit Approach to Personalized News Article Recommendation".



Logistic Bandits 101 Problem Setting

For $t \in [T]$:

- The learner observes a potentially infinite (contextual) arm-set $\mathcal{X}_t \subset \mathbb{R}^d$ 1.
- The learner chooses $x_t \in \mathcal{X}_t$ according to some policy 2.
- Receive a *binary* reward $r_t \sim \text{Ber}(\mu(\langle x_t, \theta_{\star} \rangle))$ 3.
 - θ_{\star} is unknown to the learner
 - $\mu(z) := (1 + e^{-z})^{-1}$ is the logistic function, $\dot{\mu}(z) = \mu(z)(1 \mu(z))$ is its first derivative

Minimize
$$\operatorname{Reg}^{B}(T) := \sum_{t=1}^{T} \left\{ \mu(\langle x_{t,\star}, \theta_{\star} \rangle) - \right\}$$

Goale

 $-\mu(\langle x_t, \theta_{\star} \rangle)\}, \text{ where } x_{t,\star} := \operatorname{argmax}_{x \in \mathcal{X}_t} \langle x, \theta_{\star} \rangle.$

Logistic Bandits 101 Assumptions

Assumption 1.
$$\bigcup_{t=1}^{\infty} \mathscr{X}_t \subseteq \mathbf{B}^d(1)$$

Assumption 2. $\theta_{\star} \in \mathbf{B}^d(\mathbf{S}) => \text{today's n}$

We consider the following quantities describing the difficulty of the problem:

$$\kappa_{\star}(T) := \left(\frac{1}{T} \sum_{t=1}^{T} \dot{\mu}(\langle x_{t,\star}, \theta_{\star} \rangle)\right)$$

They can scale *exponentially in S* [Faury et al., ICML'20]

nain quantity of interest!

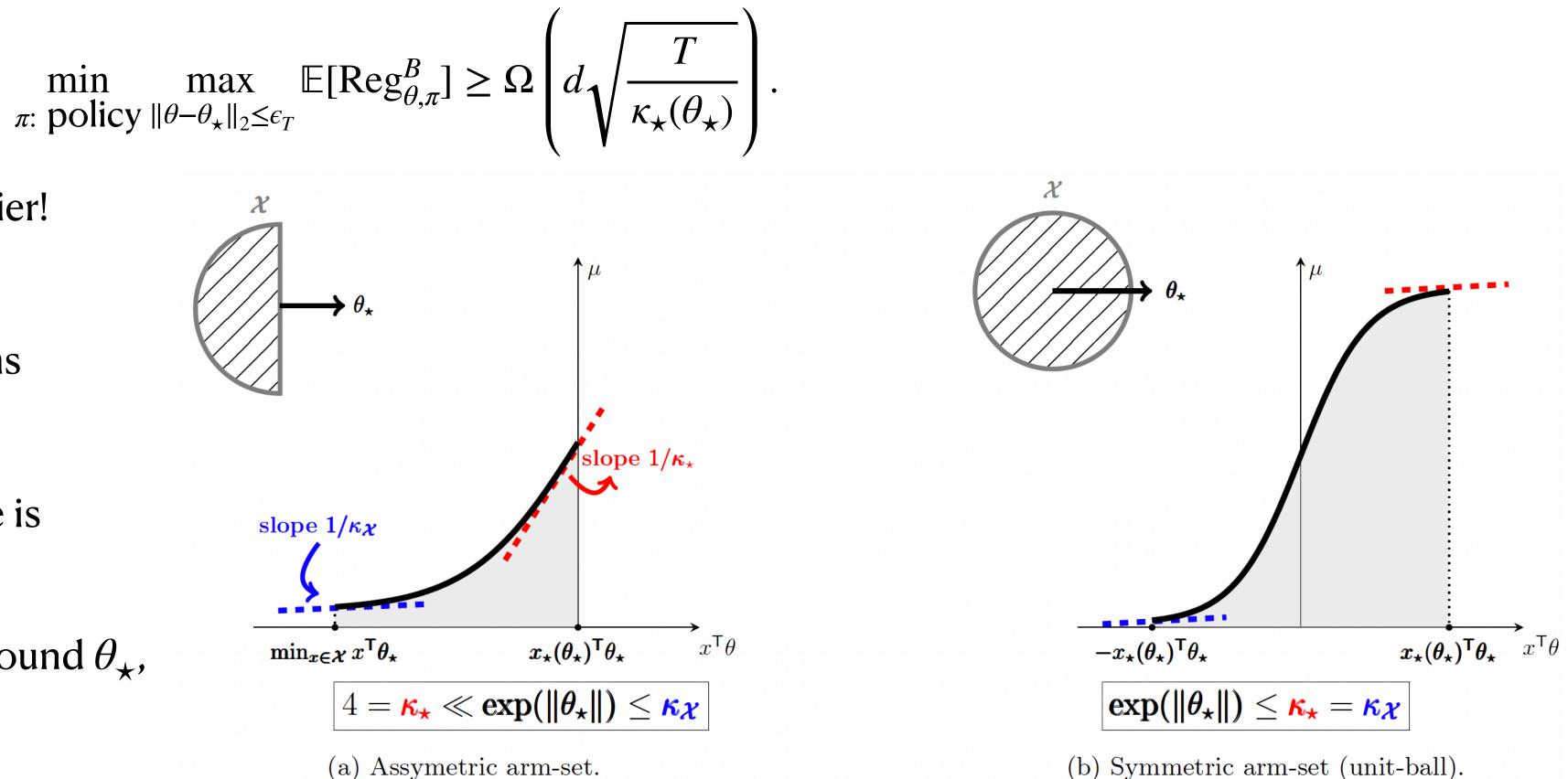
escribing the difficulty of the problem: $\int_{t\in[T]}^{-1} \kappa_{\mathcal{X}}(T) := \max_{t\in[T]} \max_{x\in\mathcal{X}_{t}} \frac{1}{\dot{\mu}(\langle x, \theta_{\star} \rangle)}.$

Logistic Bandits 101 $d\sqrt{T/\kappa_{\star}(T)}$ is minimax optimal (taken from slides of L. Faury on his website)

Theorem 2. [Local Lower-Bound; Abeille et al., AISTATS'21] Let $\mathscr{X}_t = \mathbf{S}^d(1)$ and . Then, for any problem instance θ_{\star} and for $T \ge d^2 \kappa_{\star}(\theta_{\star})$, there exists $\epsilon_T > 0$ such that:



- Transient regret (small *t*):
 - Exploration of "detrimental" arms
- Permanent regret (large *t*):
 - Sub-linear regret, as the estimate is sufficiently close to θ_{\star}
 - Linear bandit with local slope around θ_{\star} , $\dot{\mu}(\langle x_{\star}, \theta_{\star} \rangle) \sim \frac{1}{\kappa_{\star}(T)}$





Logistic Bandits 101 State-of-the-Arts, so-far

• **OFULog** [Abeille et al., AISTATS'21]. *Non-convex* confidence-set-based UCB algorithm

$$dS^{\frac{3}{2}}\sqrt{\frac{T}{\kappa_{\star}(T)}} + 1$$

• OFULog-r [Abeille et al., AISTATS'21]. Convex relaxation of OFULog ~ loss-based confidence set

$$dS^{\frac{5}{2}}\sqrt{\frac{T}{\kappa_{\star}(T)}} + 1$$

• ada-OFU-ECOLog [Faury et al., AISTATS'22]. Online Newton step [Hazan et al., 2007]-based algorithm

$$dS_{\sqrt{\frac{T}{\kappa_{\star}(T)}}} + d^2 S^6 \kappa(T)$$

Can we construct tighter (improved dependency in *S*) *loss-based confidence set*?? Can we make UCB great again (i.e., UCB-type algorithm that matches or beats ada-OFU-ECOLog)?

 $\min\left\{d^2S^3\kappa_{\mathcal{X}}(T), R_{\mathcal{X}}(T)\right\}$

 $\min\left\{d^2S^4\kappa_{\mathcal{X}}(T), R_{\mathcal{X}}(T)\right\}$

Logistic Bandits 101 More details in OFULog(-r)

• OFULog and OFULog-r are of the following form:

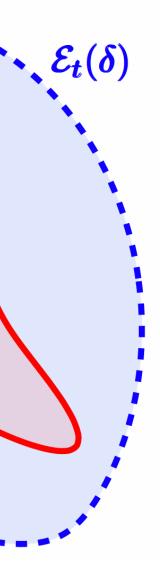
1. Solve
$$\hat{\theta}_t = \operatorname{argmin}_{\theta \in \mathbb{R}^d} \left[\mathscr{L}_t(\theta) \triangleq \sum_{s=1}^{t-1} \mathscr{L}_s(\theta) + \lambda_t \|\theta\|_2^2 \right]$$
, where $\mathscr{L}_s(\theta) := -r_s \log \mu(\langle x_s, \theta \rangle) - (1 - r_s) \log(1 - \mu(\langle x_s, \theta \rangle))$

- Obtain a confidence-set $C_t(\delta) \subseteq \mathbb{B}^d(S)$ satisfying $\mathbb{P}\left[\forall t \ge 1, \theta_{\star} \in C_t(\delta)\right] \ge 1 \delta$.
- Solve $(x_t, \theta_t) = \operatorname{argmax}_{x \in \mathcal{X}_t, \theta \in C_t(\delta)} \mu(\langle x, \theta \rangle)$, play x_t and observe/receive a reward r_t
- **OFULOG** [Abeille et al., AISTATS'21]: $C_t(\delta) := \begin{cases} \theta \in \mathbb{B}^d \end{cases}$ • **OFULog-r** [Abeille et al., AISTATS'21]: $C_t(\delta) := \begin{cases} \theta \in \mathbb{B} \end{cases}$

$${}^{d}(S): \left\| \nabla \mathscr{L}_{t}(\boldsymbol{\theta}) - \nabla \mathscr{L}_{t}(\widehat{\boldsymbol{\theta}}_{t}) \right\|_{\mathbf{H}_{t}^{-1}(\boldsymbol{\theta})} \leq \mathcal{O}\left(\sqrt{dS\log t}\right)$$

$${}^{\mathbb{B}^{d}}(S): \mathscr{L}_{t}(\boldsymbol{\theta}) - \mathscr{L}_{t}(\widehat{\boldsymbol{\theta}}_{t}) \leq \mathcal{O}\left(\sqrt{dS^{3}\log t}\right) \right\} (= E_{t}(\delta))$$

The multiplicative S's comes from rather naive applications of self-concordant ($|\ddot{\mu}| \leq \dot{\mu}$) analyses [Bach, 2010]



 $\mathcal{C}_t(\delta)$

 $\hat{\theta}_t \bullet$

Logistic
$$C_t(\delta)$$
: Gradient-based Co

- **OFULOg** [Abeille et al., AISTATS'21]: $C_t(\delta) := \left\{ \boldsymbol{\theta} \in \mathbb{B}^d(S) : \| \nabla \mathcal{L}_t(\boldsymbol{\theta}) - \nabla \mathcal{L}_t(\boldsymbol{\hat{\theta}}_t) \right\}$
- Gradient of the logistic loss:

$$\nabla \mathscr{L}_t(\theta_\star) = \sum_{s=1}^{\infty}$$

sum of martingale differences

- If $\hat{\theta}_{t}$ is a good estimator, then the gradient at θ_{\star} should be near zero!
- We can quantify "pointwise confidence" with the inverse
- Relaxing $C_t(\delta)$ to the loss-based set $E_t(\delta)$ gives a *convex* confidence set, but is not tight in S

Bandits 101

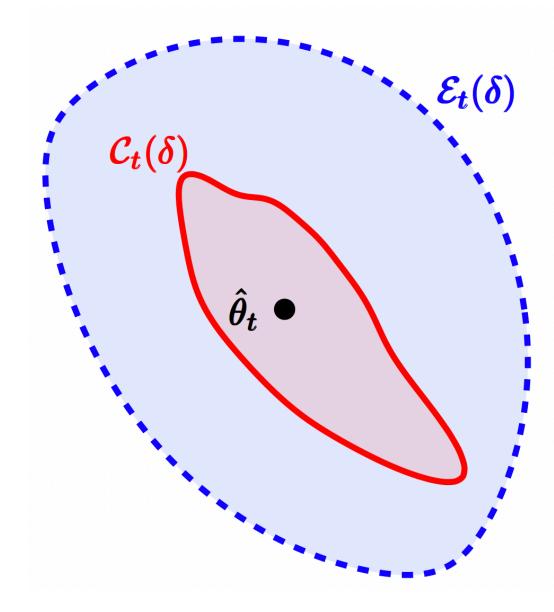
onfidence set [Abeille et al., AISTATS'21]

$$\left\| \left\|_{\mathbf{H}_{t}^{-1}(\boldsymbol{\theta})} \leq \mathcal{O}\left(\sqrt{dS\log t}\right) \right\}$$

$$u(\langle x_s, \theta_{\star} \rangle) - r_s) x_s + 2\lambda_t \theta_{\star}$$

e of Hessian (covariance)
$$H(\theta_{\star}) = \sum_{s=1}^{t-1} \dot{\mu}(\langle x_s, \theta_{\star} \rangle) x_s x_s^{\top} + \lambda I$$

• In order to obtain a confidence set, we require the local metric $\|\cdot\|_{\mathbf{H}_{t}^{-1}(\theta)}$ that depends on the choice of θ





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achievable online learning regret bound (without ever running the alg), and apply it to





Regret-to-Confidence-Set Conversion (R2CS) Main Theorem - Improved Confidence Set for Logistic Loss

• Let us consider norm-constrained, unregularized MLE: $\widehat{\theta}_{t} := \operatorname{argmin}_{\theta \in \mathbb{B}^{d}(S)} \left| \mathscr{L}_{t}(\theta) := \sum_{s=1}^{t-1} \mathscr{\ell}_{s}(\theta) \right|, \text{ where } \mathscr{\ell}_{s}(\theta) := -$

Theorem 1. [Lee et al., AISTATS'24] We have $\mathbb{P} \quad \forall t \geq t$ $C_t(\delta) := \left\{ \theta \in \mathbb{B}^d(S) \right\}$ $\beta_t(\delta) := \sqrt{10d \log\left(\frac{St}{4d} + e\right) + 2}$

Strict improvement over prior (loss-based & convex) confidence-set radius of $\mathcal{O}\left(\sqrt{dS^3 \log t}\right)$

$$-r_s \log \mu(\langle x_s, \theta \rangle) - (1 - r_s) \log(1 - \mu(\langle x_s, \theta \rangle))$$

1,
$$\theta_{\star} \in C_t(\delta)] \ge 1 - \delta$$
, where

$$: \mathscr{L}_t(\theta) - \mathscr{L}_t(\widehat{\theta}_t) \le \beta_t(\delta)^2 \},$$

$$2((e-2) + S)\log\frac{1}{\delta} = \mathcal{O}(\sqrt{(d+S)\log t})$$



Decomposing the logistic loss with any online learning algorithm
$$\tilde{\theta}_s$$
:

$$\mathscr{L}_t(\theta_\star) - \mathscr{L}_t(\hat{\theta}_t) = \sum_{s=1}^{t-1} \ell_s(\theta_\star) - \ell_s(\hat{\theta}_t) = \sum_{s=1}^{t-1} \left(\ell_s(\tilde{\theta}_s) - \ell_s(\hat{\theta}_t) \right) + \sum_{s=1}^{t-1} \left(\ell_s(\theta_\star) - \ell_s(\tilde{\theta}_s) \right)$$
where $\zeta_1(t) := \sum_{s=1}^{t-1} \xi_s \langle x_s, \tilde{\theta}_s - \theta_\star \rangle$, $\zeta_2(t) := \sum_{s=1}^{t-1} \operatorname{KL}(\mu_s(\langle x_s, \theta_\star \rangle), \mu_s(\langle x_s, \tilde{\theta}_s \rangle))$

- with high probability since θ_{\star} is the problem instance parameter.

• $\operatorname{Reg}^{O}(t)$ is the online regret up to time t, and $\zeta(t)$ is the superiority of the online learning algorithm in terms of loss compared to θ_{\star} which is expected very small (independent to t)

• $\hat{\theta}_t$ is the optimal parameter for the entire batch til time *t*, while $\tilde{\theta}_s$ is the online prediction.



- 1. Decomposing the logistic loss such that the $\beta_t(\delta)^2$ is expressed as a sum of Reg⁰(*t*), regret of *any* online learning algorithm of our choice, $\zeta_1(t)$, a sum of martingales, and $-\zeta_2(t)$, a (negative) sum of KL-divergences.
- 2. For $\text{Reg}^{O}(t)$, we utilize the state-of-the-art online regret of Foster et al., (COLT'18), which reduces the usual dS to $d \log S$, without ever running the algorithm.
- 3. For $\zeta_1(t)$, we utilize a novel anytime variant of the Freedman's concentration inequality [Freedman, 1975] for martingales.
- 4. For $-\zeta_2(t)$, we utilize the Bregman geometrical interpretation of the KL-divergence, along with self-concordant results.



1. divergences.

Note that
$$r_s = \mu(\langle x_s, \theta_{\star} \rangle) + \xi_s$$
 for some **Lemma 1 & 2.** [Lee et al., AISTATS'24] For the

$$\sum_{s=1}^{t} \ell_s(\theta_\star) - \ell_s(\hat{\theta}_t)$$

Decomposing the logistic loss such that the $\beta_t(\delta)^2$ is expressed as a sum of Reg⁰(t), regret of any online learning algorithm of our choice, $\zeta_1(t)$, a sum of martingales, and $-\zeta_2(t)$, a (negative) sum of KL-

- martingale difference noise ξ_s .
- logistic loss ℓ_s and *any* sequence of parameters $\{\hat{\theta}_s\}$ (e.g., "outputted" from some online algorithm), the following holds:

 $\leq \operatorname{Reg}^{O}(t) + \zeta_{1}(t) - \zeta_{2}(t)$. The proof utilizes second-

order Taylor expansion of ℓ_s with *integral remainder*!



2. For $\operatorname{Reg}^{O}(t)$, we utilize the state-of-the-art online dS to $d \log S$, without ever running the algorithm.

Theorem 3. [Foster et al., COLT'18] There exists an (improper learning) algorithm for online logistic regression with the following regret:

 $\operatorname{Reg}^{O}(t) \leq 10$

Note how we get *d* log *S* instead of *dS*!! Even better, we get this *without ever running the algorithm*, which in this case, is quite expensive!

For $\operatorname{Reg}^{O}(t)$, we utilize the state-of-the-art online regret of Foster et al., (COLT'18), which reduces the usual

$$Dd \log\left(\frac{St}{4d} + e\right).$$



- 3.
- **Lemma 3.** [Lee et al., AISTATS'24] Let $\{X_s\}_{s=1}^t$ be a martingale difference sequence satisfying max $|X_s| \leq R$ a.s., and let $\mathscr{F}_s := \sigma(X_1, \dots, X_s)$. Then for any $\delta \in (0,1)$ and any $\eta \in [0,1/R]$, the following holds: $\mathbb{P}\left[\forall t \ge 1, \sum_{s=1}^{t} X_s \le (e-2)\eta \sum_{s=1}^{t} \mathbb{E}[X_s^2 \mid \mathcal{F}_{s-1}] + \frac{1}{\eta} \log \frac{1}{\delta}\right] \ge 1 - \delta.$ The proof is based on Theorem 1 of Beygelzimer et With this, we have the following: for any choice of $\delta \in (0,1)$ and $\eta \in \begin{bmatrix} 0, \frac{1}{2S} \end{bmatrix}$, al. (ICML'11) and the Ville's inequality [Ville, 1939] $i(\langle x_s, \theta_\star \rangle) \langle x_s, \theta_\star - \tilde{\theta}_s \rangle^2 + \frac{1}{\eta} \log \frac{1}{\delta} \ge 1 - \delta$

$$\mathbb{P}\left[\forall t \ge 1, \, \zeta_1(t) \le (e-2)\eta \sum_{s=1}^t \dot{\mu}(s)\right]$$

For $\zeta_1(t)$, we utilize a novel anytime variant of the Freedman's concentration inequality [Freedman, 1975] for martingales.



4. concordant results.

Observation.
$$D_m(z_1, z_2) := m(z_1) - m(z_2) - \nabla m(z_2)^{\mathsf{T}}(z_1 - z_2) = \int_{z_1}^{z_2} m''(z)(z_1 - z)dz.$$

For $-\zeta_2(t)$, we utilize the Bregman geometrical interpretation of the KL-divergence, along with self-

Lemma 4. [Lee et al., AISTATS'24] $KL(\mu(z_1), \mu(z_1)) = D_m(z_1, z_2)$, where $m(z) := \log(1 + e^z)$.

Combining above with self-concordant analysis [Lemma 8 of Abeille et al., AISTATS'21], we have:

$$-\zeta_2(t) \le -\frac{1}{2+2S} \sum_{s=1}^{1} \dot{\mu}(\langle x_s, \theta_\star \rangle) \langle x_s, \theta_\star - \tilde{\theta}_s \rangle^2$$



Combining everything, we have: with probability at least $1 - \delta$, for all $t \in [T]$,

$$\begin{split} &\sum_{s=1}^{t} \ell_{s}(\theta_{\star}) - \ell_{s}(\widehat{\theta}_{t}) \\ &\leq \operatorname{Reg}^{O}(t) + \zeta_{1}(t) - \zeta_{2}(t) \\ &\leq 10d \log\left(\frac{St}{4d} + e\right) + (e - 2)\eta \sum_{s=1}^{t} \dot{\mu}(\langle x_{s}, \theta_{\star} \rangle) \langle x_{s}, \theta_{\star} - \widetilde{\theta}_{s} \rangle^{2} + \frac{1}{\eta} \log \frac{1}{\delta} - \frac{1}{2 + 2S} \sum_{s=1}^{t} \dot{\mu}(\langle x_{s}, \theta_{\star} \rangle) \langle x_{s}, \theta_{\star} - \widetilde{\theta}_{s} \rangle \\ &\leq 10d \log\left(\frac{St}{4d} + e\right) + 2((e - 2) + S) \log \frac{1}{\delta}, \end{split}$$

where we choose $\eta = \frac{1}{2(e-2)+2S} < \frac{1}{2S}$ that satisfy

sfies
$$-\frac{1}{2+2S} + \frac{e-2}{2(e-2)+2S} < 0.$$





Related Work: Online-to-Something Conversions Online Learning -> Concentration of Measure

Online-to-confidence-set: Start from some online learning algorithm *A* with regret s=1depends on the outputs of \mathcal{A} whose radius scales with B(t) [Abbasi-Yadkori et al., AISTATS'12; Jun et al., NeurIPS'17]

directly translates into tighter confidence sets" [Abbasi-Yadkori et al., AISTATS'12]; see Chapter 23.3 of Lattimore and Szepesvári (2020)

worse regret & good computational complexity [Jézéquel et al., COLT'20]

Our algorithm does not run the online learning part!

- $\sum \ell_s(\theta_s) \ell_s(\theta_\star) \leq B(t)$, then bound LHS to obtain a quadratic-type confidence set on θ_\star that
- Advantages of O2SC: "progress in constructing better algorithms for online prediction problems
- **BUT**, what if the online learning has a trade-off between computational complexity and regret?? e.g., online logistic regression: good regret & bad computational complexity [Foster et al., COLT'18] or



Related Work: Online-to-Something Conversions Online-to-PAC Conversion

Recently, Lugosi & Neu (arXiv'23) introduced online-to-PAC conversion:

"... the *existence* of an online learning algorithm with bounded regret in this game implies a bound on the generalization error of the statistical learning algorithm up to a martingale concentration term that is independent of the complexity of the statistical learning method."

=> very similar spirit, but the goal is different from ours.

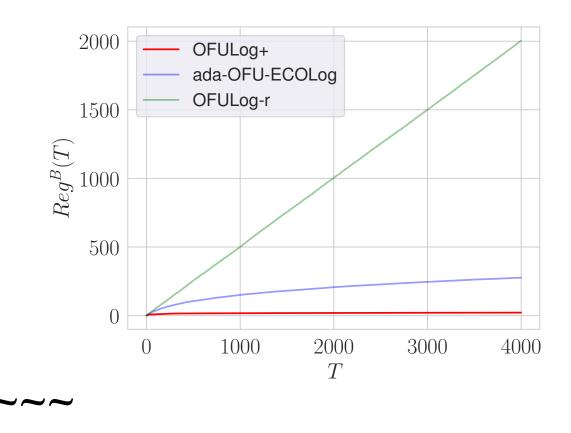


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Improved Regret of Logistic Bandits **OFULog+**

Theorem 3. [Lee et al., AISTATS'24] OFULog+ incurs the following regret bound w.p. at least $1 - \delta$:

$$\operatorname{Reg}^{B}(T) \lesssim dS_{\sqrt{\frac{T}{\kappa}}}$$

permanent term

(Refer to our paper for the missing definitions)

• Note that our algorithm is of the same form with OFULog-r, except we've only changed the confidence set radius, $\mathcal{O}\left(\sqrt{dS^3 \log t}\right)$ to $\mathcal{O}\left(\sqrt{(d+S)\log t}\right)$, which we call *OFULog*+

+ min
$$\left\{ d^2 S^2 \kappa_{\mathcal{X}}(T), R_{\mathcal{X}}(T) \right\}$$

transient term



Improved Regret of Logistic Bandits **OFULog+** is the state-of-the-art, taking S into account

• **OFULOg** [Abeille et al., AISTATS'21]. *Non-convex* confidence-set-based UCB algorithm

• **OFULog-r** [Abeille et al., AISTATS'21]. Convex relaxation of OFULog

 $dS^{\frac{5}{2}}\sqrt{\frac{T}{\kappa_{\star}(T)}} + \min\left\{d^2S^4\kappa_{\mathcal{X}}(T), R_{\mathcal{X}}(T)\right\}$

• ada-OFU-ECOLog [Faury et al., AISTATS'22]. Online Newton step (ONS) [Hazan et al., 2007]-based algorithm

$$dS_{\sqrt{\frac{T}{\kappa_{\star}(T)}}} + d^2 S^6 \kappa(T)$$

• **OFULog**+ [Lee et al., AISTATS'24]. Tight loss-based confidence set

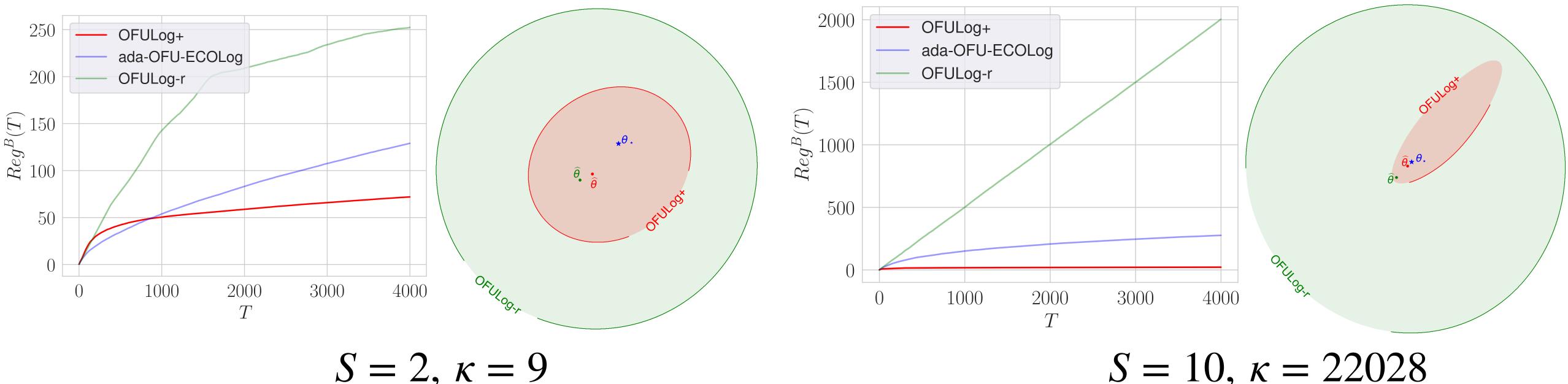
$$dS\sqrt{\frac{T}{\kappa_{\star}(T)}} + n$$

 $dS^{\frac{3}{2}}\sqrt{\frac{T}{\kappa_{\star}(T)}} + \min\left\{d^2S^3\kappa_{\mathcal{X}}(T), R_{\mathcal{X}}(T)\right\}$

 $\min\left\{d^2S^2\kappa_{\mathcal{X}}(T), R_{\mathcal{X}}(T)\right\}$

Improved Regret of Logistic Bandits **Experiments**

- One may wonder, does shaving off dependencies on S really help in practice?
- Synthetic experiments show that this is indeed beneficial, by a large margin!!
 - (In fact, we believe that the current analysis can be made tighter, which may explain the large margin lacksquareshown in the experiments)



 $S = 2, \kappa = 9$

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Conclusion and Future Works Conclusion

- 1. explicitly.
- state-of-the-art regret guarantee of logistic bandits.
- 3. performance.

Omitted from this presentation:

- Guarantees for multinomial logistic loss/bandits
- Extensive discussions on other related work
- and more

Regret-to-confidence-set conversion (R2CS): a new framework that converts an *achievable* online learning regret guarantee to a confidence set, without ever running the online algorithm

2. We apply R2CS to obtain tightest confidence set for logistic losses, which then leads to the

We empirically show that our new confidence-set based UCB algorithm attains the best

Conclusion and Future Works Future Works

- 1. AISTATS'22], and multinomial logistic MDPs [Hwang & Oh, AAAI'23].
- 2. & Sun, ICLR'24] tighter?
- Any relation to Thompson sampling [Abeille & Lazaric, 2017]? 3.
- 4. confidence set [Emmenegger et al., NeurIPS'23]?
- Any relation to Decision Estimation Coefficients [Foster et al., arXiv'21]? 5.
- ...etc!! 6.

Extend our R2CS framework to various settings such as sparse logistic bandits [Oh et al., ICML'21], generalized linear bandits [Filippi et al., NIPS'10], norm-agnostic scenario [Gales et al.,

As logistic bandits can be seen as utility-based dueling bandits with top-1 feedback (Bradley-Terry model), apply our analysis to make the recent guarantees on RLHF [Wu

Any relation to universal inference [Wasserman et al., 2020] and sequential likelihod ratio

Thank you for your attention!



(arXiv will be updated with camera-ready ver soon)

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References Related Work, Future Work

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