


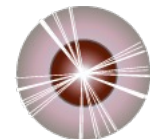
KCC 2022

A Statistical Analysis of Stochastic Gradient Noises for GNNs

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1. Introduction

Most of the optimization problems in ML/DL can be expressed as the following formulation:

$$\min_w F(w) \triangleq \min_w \frac{1}{n} \sum_{i=1}^n f^{(i)}(w)$$

, where summands are the individual loss contributed by each data point or minibatch.

- This optimization problem is usually solved via stochastic version of gradient descent method, called the stochastic gradient descent (SGD).

$$w_{t+1} = w_t - \eta \nabla \tilde{f}_k(w_t) = w_t - \eta \nabla F(w_t) + \eta U_t$$

$$(\nabla \tilde{f}_k(w) = (1/|\Omega_k|) \sum_{i \in \Omega_k} \nabla f^{(i)}(w) , U_t(w) = \nabla F(w) - \nabla \tilde{f}_k(w))$$

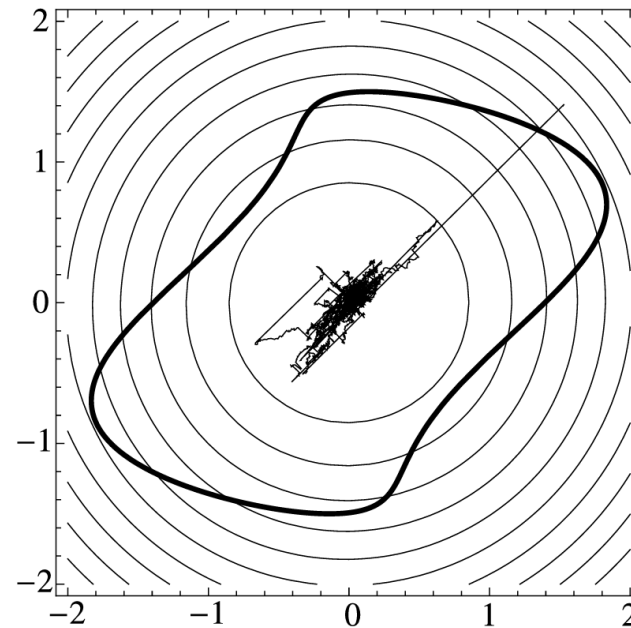
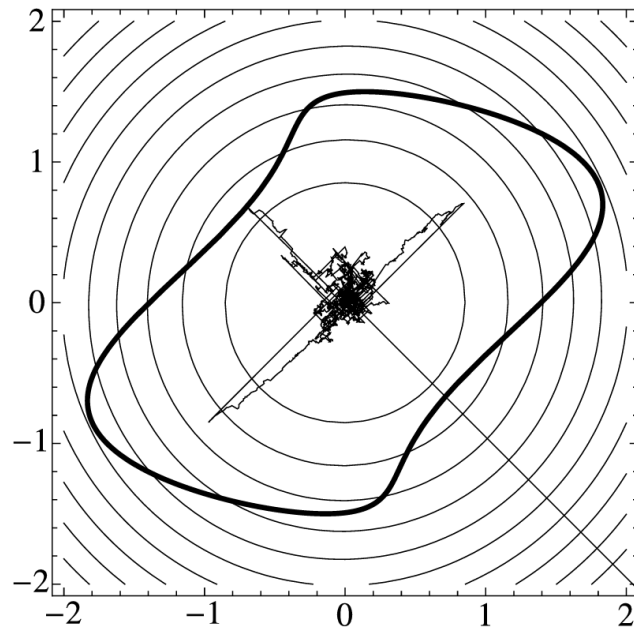
- Computationally efficient
- The noises of SGD contribute towards better generalization capability of the resulting model.
 - Empirical studies: [Keskar et al., ICLR'16] [Smith et al., ICML'20] ...etc.
 - Theoretical studies: [Pesme et al., NeurIPS'21] [Damian et al., NeurIPS'21] ...etc.

$$w_{t+1} = w_t - \eta \nabla \tilde{f}_k(w_t) = w_t - \eta \nabla F(w_t) + \eta U_t$$

- Depending on the empirical observation and/or modeling assumption, one can either choose to model the stochastic gradient noise(SGN) U_t as normal or heavy-tailed.
- Precisely speaking, this distinction comes from whether that the second moment of U_t is finite or infinite.
 - Heuristically, with big enough batch size, we can invoke the (generalized) central limit theorem, depending on the assumption.

- The importance of such assumption is highlighted when we analyze SGD via its counterpart SDE.
 - Under appropriate limit (vanishing learning rate, big enough batch size), we can analyze the SGD in the continuous regime.
 - Close connection with the stochastic gradient Langevin dynamics. [Welling & Teh, ICML'11] [Mandt et al., JMLR 2017]
- The stochastic process driving that SDE thus depends on the assumption!
 - SGD as Brownian-driven SDE: [Li et al., JMLR 2019] [Li et al., NeurIPS'21]
 - SGD as Levy-driven SDE: [Simsekli et al., ICML'19] [Zhou et al., NeurIPS'20]

- The behaviors of these SDEs are completely different (see [Simsekli et al., ICML'19] and references therein for more details)



- Therefore, by empirically measuring the tail property of SGN, we can expect the characteristic of training process.
- This was first proposed in [Simsekli et al., ICML'19]:

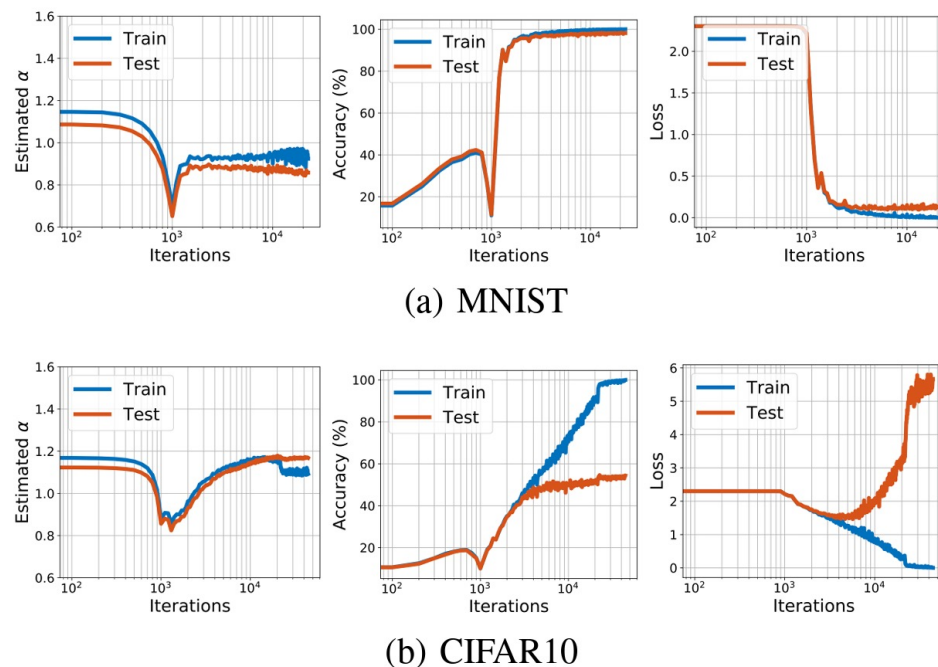
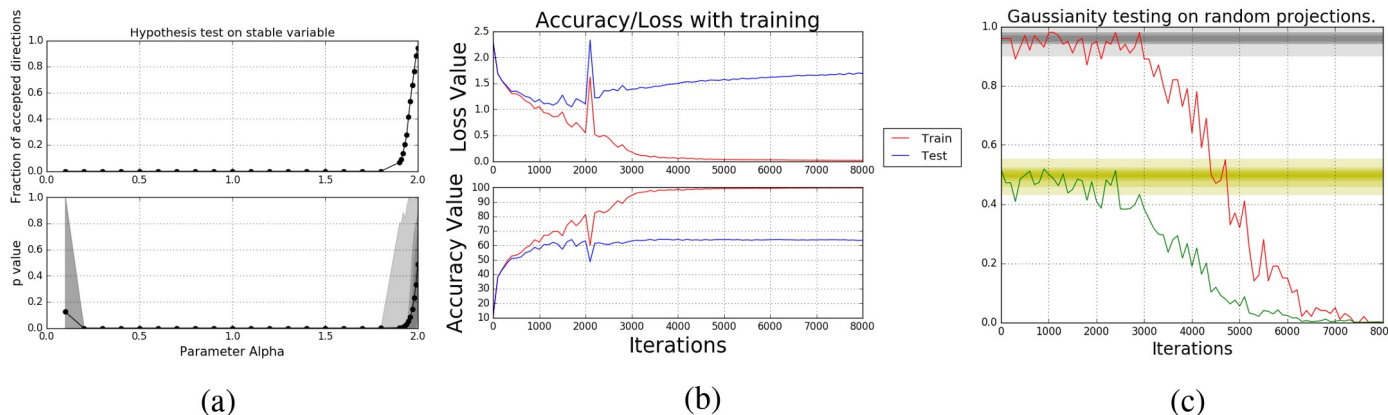


Figure 7. The iteration-wise behavior of α for the FCN.

- Preliminary statistical tests [Panigrahi et al., NeurIPS'19] showed that the heavy-tailedness depends heavily on the hyperparameters



- A more sophisticated statistical analysis [Wang et al., ICLR'22] showed that actually, the SGN often displays the behavior of lognormal distribution

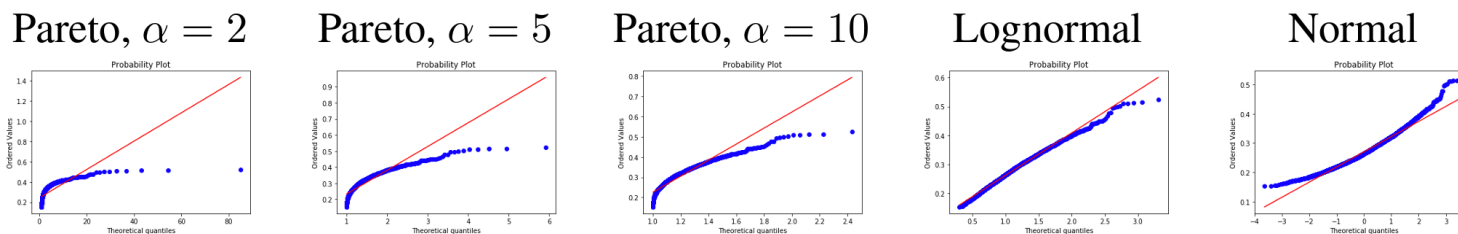


Figure A.7: Ablation Study, Corrupted FMNIST & LeNet: At the beginning

- Despite the abundance of literature in analyzing stochastic optimization, not much work has been done that analyzes stochastic training process on the Graph Neural Network (GNN).
- Therefore, as the first step, we would like to tackle the following question:

What are the statistical properties of SGNs when we perform stochastic training of GNNs?

2. Problem Settings

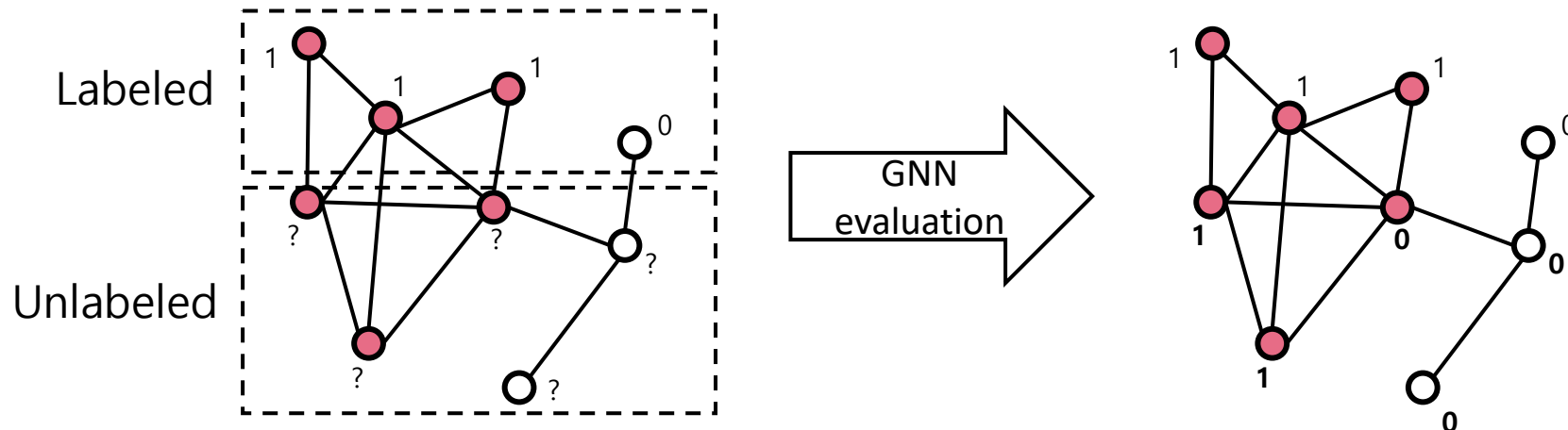
- Graph Neural Network (GNN) transforms node feature from the original graph. We can use transformed feature to various machine learning tasks.
- Several aggregation schemes have proposed, including the famous two methods:

$$\text{GCN: } h'_v = \text{RELU} \left(\sum_{u \in N(v)} W \frac{h_u}{|N(v)|} + h_v \right)$$

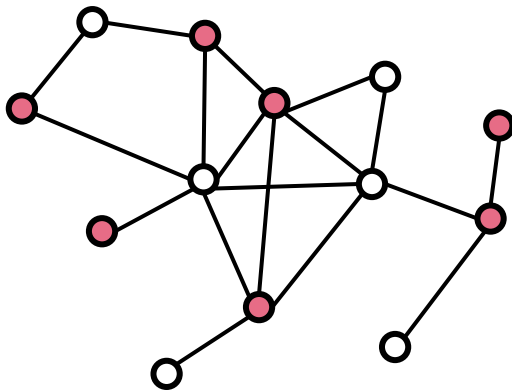
$$\text{GIN: } h'_v = \text{MLP}_\Phi \left((1 + \epsilon) \cdot \text{MLP}_f(h_v) + \sum_{u \in N(v)} \text{MLP}_f(h_u) \right)$$

2. Problem Settings

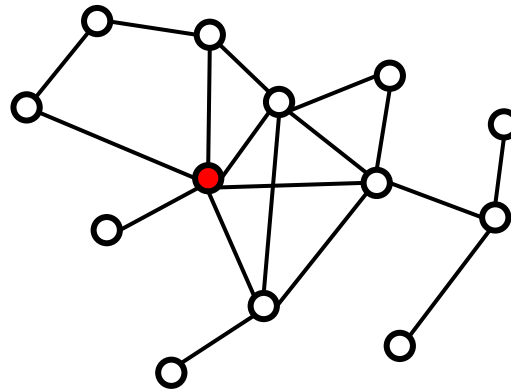
- We used the semi-supervised node classification setting: Given partial labeled vertices, we should predict the label of the left unlabeled vertices after training.



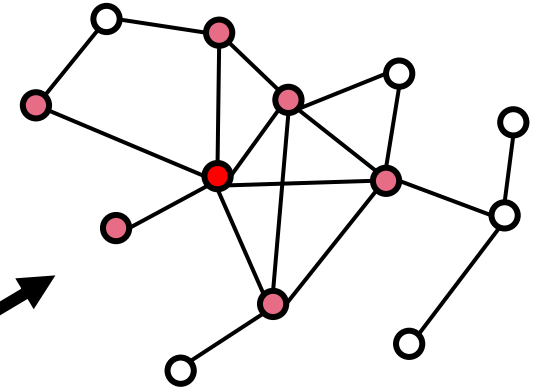
- There are two methods of sampling nodes: (1) node batching and (2) neighborhood sampling.
- We consider uniformly random node batching *without* neighborhood sampling.
 - This is to isolate such additional effect



(1) Randomly select N



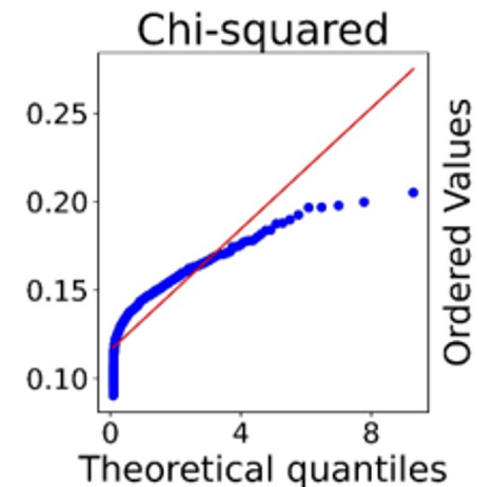
(2-1) Randomly select one



(2-2) Select neighbors

3. Experimental Settings

- At prescribed epochs, we measured the norms of the SGNs, which are then formed from 1000 random batches.
 - We consider three epochs: beginning, middle, and end (see the paper for more details)
- We visualize the SGN norm distribution to some predefined distribution (e.g., normal, log normal, Pareto) using **QQ-plots**. [Wang et al., ICLR'22]
- We use the Cora dataset.



4. Results

4.Results (GCN)

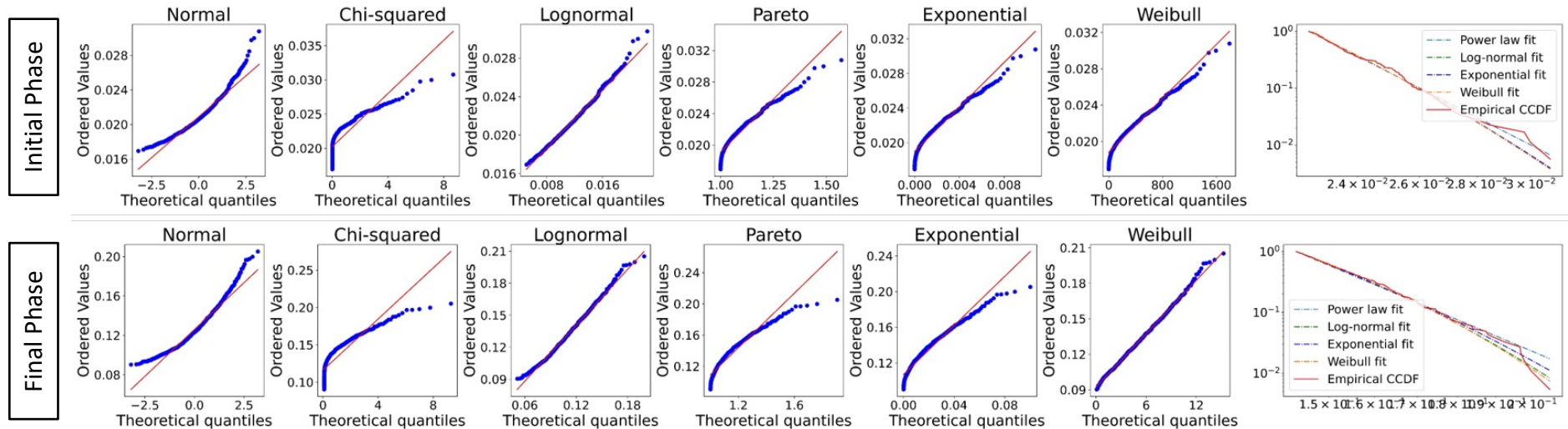


그림 1 (GCN)

- Normal and Pareto(Power law) distributions do *not* fit well, while Log Normal distribution has good fit. → This is in line with the observations for vision tasks [Wang et al., ICLR'22].
- Chi-squared distribution does not fit well.

4.Results (GIN)

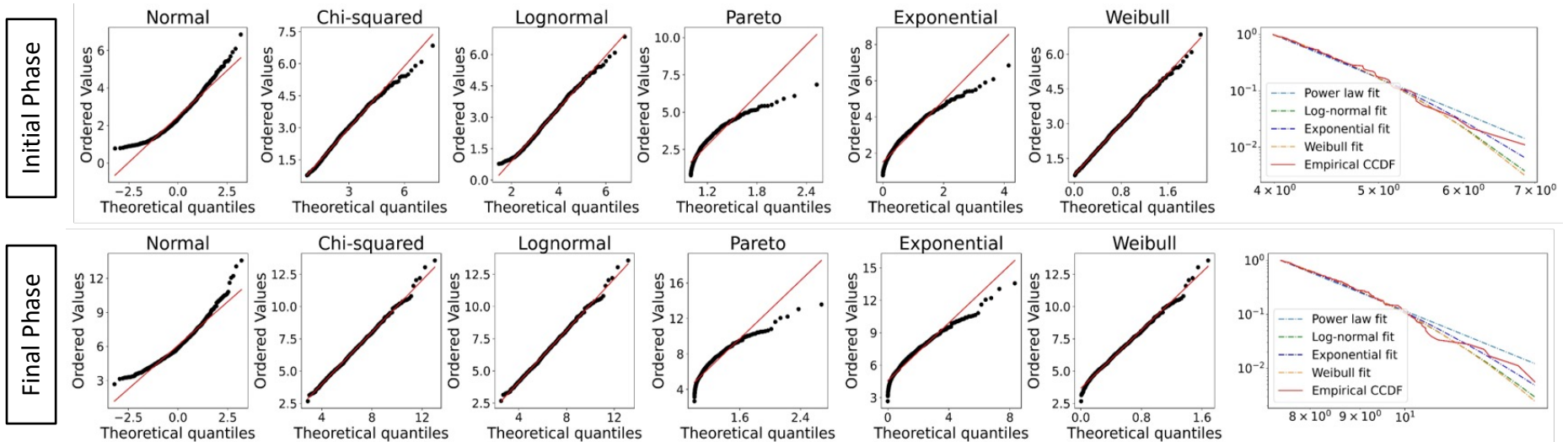


그림 2 (GIN)

- Similar as GCN i.e. normal and Pareto provide poor fits, while lognormal provides somewhat good fit.

Chi-squared distribution does fit well.

→ **Chi-squared fitting distinguish the GCN and GIN.**

Takeaways/Future Works

- We provide a preliminary statistical analysis of SGN of GNNs, following [Wang et al., ICLR'22].
- The statistical behaviors of SGD for GNNs are similar with that for the common vision tasks.
- According to chi-squared distribution "test", tail properties of GCN and GIN differ.
 - Is this reliable conclusion? Their behaviors are the same for normal, Pareto (in that those two do not fit well), and lognormal (in that this provides good fit)
- The most interesting future direction would be to see whether specific graph properties can be incorporated into the dynamics of SGD (e.g. degree distribution, graph topology...etc)
 - This has been recently done for distributed learning setting [Gurbuzbalaban et al., arXiv'22]

Thank you



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