

On the Estimation of Linear Softmax Parametrized Markov Chains

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Optimization and
Statistical Inference LAB

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- ▶ Softmax parametrization is highly ubiquitous when one wishes to estimate discrete probability distribution.
- ▶ Due to its simplicity, it is employed in a wide range of applications such as multinomial logistic Markov Decision Processes [HO23], deep learning [S⁺21], and human decision-making [RL15].
- ▶ In this work, we compare three distinct choices of softmax-type parametrization of a **transition probability distribution**.

Problem Setup

- ▶ Given a finite set \mathcal{S} with $|\mathcal{S}| = N$, let $P \in \Delta(\mathcal{S})$ where $\Delta(\mathcal{S})$ denote the set of all transition probability distributions over \mathcal{S} .
- ▶ For example, if $\mathcal{S} = \{s_1, \dots, s_N\}$, $P(\cdot | s_i)$ is the probability distribution over \mathcal{S} given that the current state is s_i .
- ▶ The transition probability distribution P can be canonically identified as an element of $\text{Mat}_{N \times N}(\mathbb{R})$.
- ▶ We analyze three softmax-type parametrizations of P that exploit $\text{softmax} : \mathbb{R}^N \rightarrow \mathbb{R}$ to generate probability distributions $P(\cdot | s)$ for each $s \in \mathcal{S}$.

Softmax-type parametrizations

In this work, we provide theoretical and empirical analyses on three popular ways to estimate P , which are summarized below.

1. $p(s' | s) = \text{softmax}(\{\varphi(s)^\top \theta_\star(s')\}_{s'})$, where $\varphi : \mathcal{S} \rightarrow \mathbb{R}^d$ is *known* and $\theta_\star : \mathcal{S} \rightarrow \mathbb{R}^d$ is *unknown*.
2. $p(s' | s) = \text{softmax}(\{\varphi(s, s')^\top \theta_\star\}_{s'})$, where $\varphi : \mathcal{S} \times \mathcal{S} \rightarrow \mathbb{R}^d$ is *known* and $\theta_\star \in \mathbb{R}^d$ is *unknown*.
3. $p(s' | s) = \text{softmax}(\{\varphi(s, s')^\top \theta_\star\}_{s'})$, where $\varphi : \mathcal{S} \times \mathcal{S} \rightarrow \mathbb{R}^d$ is *unknown* and $\theta_\star \in \mathbb{R}^d$ is also *unknown*.

In any case, we are given a trajectory (X_1, \dots, X_T) of length T , where

$$X_1 \sim \mu, \quad X_{t+1} \sim p(\cdot | X_t), \quad t = 1, 2, \dots, T-1.$$

Here, μ is some unknown probability distribution over \mathcal{S} .

We consider the performance of two MLE's:

► **Non-parametric model:**

$$\hat{p}_{\text{nonparam}}(s' | s) = \frac{\#[s \rightarrow s']}{\#[s]}, \quad \forall s, s' \in \mathcal{S}.$$

This is known to be minimax over ergodic Markov chains [WK21].

► **Parametric model:**

$$\hat{p} := p_{\hat{\theta}_T}, \quad \hat{\theta}_T = \operatorname{argmax}_{\theta \in \mathbb{R}^d} \sum_{t=1}^T \left\{ \log p_{\theta}(X_{t+1} | X_t) \right\}.$$

One reasonable expectation is that when d is small, the latter MLE may be able to break the barrier of the minimax rate.

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We say that the parametrization scheme is **fully expressive** if every Markov chain can be expressed as that scheme.

Theorem 2.1 (Informal Version)

The **parametrizations #1, #2, #3** are fully expressive if there are no irrelevant or redundant features.

The formal statement can be organized as

Param #1 is fully expressive when: the linear equation $L_{\Phi}x = y$ has solution for $\forall y \in \mathbb{R}^d$	Param #2, #3 are fully expressive when: the linear equation $L_{\Psi}x = y$ has solution for $\forall y \in \mathbb{R}^d$
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where we define

$$\Phi = \begin{bmatrix} \varphi(s_1)^{\top} \\ \vdots \\ \varphi(s_N)^{\top} \end{bmatrix} \in \text{Mat}_{N,d}(\mathbb{R}), \quad \Psi = \begin{bmatrix} \Phi(s_1) \\ \vdots \\ \Phi(s_N) \end{bmatrix} \in \text{Mat}_{N^2,d}(\mathbb{R})$$

for parametrization #1 and {#2, #3}, respectively. Here, for parametrizations #2 and #3, $\Phi(s)$ is defined by

$$\Phi(s) = [\varphi(s, s_1)^{\top} \cdots \varphi(s, s_N)^{\top}]^{\top} \in \text{Mat}_{N,d}(\mathbb{R}).$$

- ▶ An accurate estimate of θ_* yields an accurate estimate of p_{θ_*} .
- ▶ An inaccurate estimate $\hat{\theta}$ of θ_* might still yield a good estimate of p_{θ_*} , due to the translation invariance of softmax. [**Non-identifiability**]

Theorem 2.2 (Accurate $\theta \Rightarrow$ Accurate p_θ ; Parametrization #1)

Assume that the true transition probability distribution has representation $p_{\theta_*}(s'|s) = \text{softmax}\{\{\varphi(s)^\top \theta_*(s')\}_{s'}\}$, and consider the parametrization $p_\theta(s'|s) = \text{softmax}\{\{\varphi(s)^\top \theta(s')\}_{s'}\}$. Then, one has that

$$\|p_\theta - p_{\theta_*}\|_{\infty,1} := \max_{s \in \mathcal{S}} d_{\text{TV}}(p_\theta(\cdot|s), p_{\theta_*}(\cdot|s)) \lesssim \frac{N}{2} \|\theta - \theta_*\|_{\infty,2}.$$

Theorem 2.3 (Accurate $\theta \Rightarrow$ Accurate p_θ ; Parametrization #2)

Consider the parametrization $p_\theta(s'|s) = \text{softmax}(\{\varphi(s, s')^\top \theta\}_{s'})$, where $\varphi : \mathcal{S} \times \mathcal{S} \rightarrow \mathbb{R}^d$ is known. Assume that the true transition probability distribution has representation $p_{\theta_*}(s'|s) = \text{softmax}(\varphi(s, s')^\top \theta_*)$. Then, one has that

$$\|p_\theta - p_{\theta_*}\|_{\infty,1} \lesssim \frac{1}{2} \|\theta - \theta_*\|_2.$$

Proposition 1 (Non-identifiability, Parametrization #1)

If $\mathbf{1}_{\mathbb{R}^d} \in \text{Ran } L_\Phi$, then for any $\varepsilon > 0$, there exists a $\tilde{\theta}_\star : \mathcal{S} \rightarrow \mathbb{R}^d$ such that $p_{\theta_\star} = p_{\tilde{\theta}_\star}$, yet $\|\theta_\star - \tilde{\theta}_\star\|_{\infty,2} \geq \varepsilon$.

Proposition 2 (Non-identifiability, Parametrization #2 & #3)

If $\mathbf{1} = \mathbf{1}_{\mathbb{R}^d} \in \text{Ran } L_\Psi$, then for any given $\varepsilon > 0$, there exists some $\tilde{\theta}_\star$ such that $p_{\theta_\star} = p_{\tilde{\theta}_\star}$, yet $\|\theta_\star - \tilde{\theta}_\star\|_2 \geq \varepsilon$.

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Setup

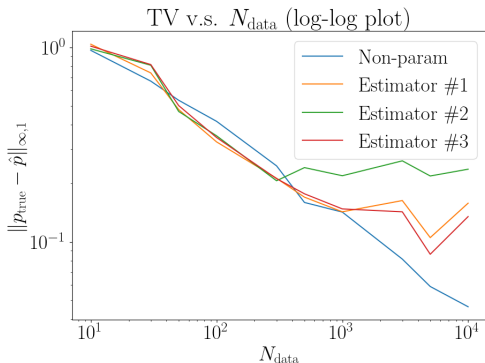
- ▶ We consider a Markov chain $\mathbb{M} = (\mathcal{S}, \mu, P)$ with $N = 10$ states and (randomly generated) fixed μ and P .
- ▶ We consider the non-parametric estimator and three distinct parametric estimators.
- ▶ For each parametric estimators, we perform the maximum likelihood estimator w.r.t. θ : precisely speaking,

$$\underset{\theta \in \mathbb{R}^d}{\text{maximize}} \quad \sum_{t=1}^T \log p_{\theta}(X_{t+1} | X_t)$$

via gradient ascent on θ with the learning rate of 0.003.

Experiment #1

We vary the number of data points N_{data} over a set of values: $N_{\text{data}} \in \{10, 30, 100, 300, 1000, 3000, 10000, 30000\}$, and observe the decay rate of the metric $\|p_\theta - P\|_{\infty,1}$.



- ▶ For $N_{\text{data}} \leq 10^3$, we observe the slope of $-1/2$ on the log-log plot, indicating a decay rate of $\mathcal{O}(N_{\text{data}}^{-1/2})$.
- ▶ As N_{data} increases, the absolute value of the slope for parametric estimators decreases, indicating improved performance compared to the non-parametric estimator.

Experiment #2

In this experiment, we observe the decay rate of the discrepancy metric $\|p_\theta - P\|_{\infty,1}$ over the number of epochs.

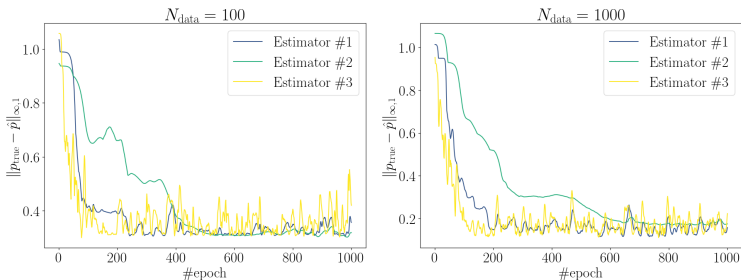


Figure: (Left) training curve for $N_{\text{data}} = 100$, (Right) training curve for $N_{\text{data}} = 1000$

- In both figures, the first and third estimators demonstrate superior performance compared to the second estimator, while the second estimator exhibits greater robustness.

Future work

- ▶ Theoretically exploring the decay rate of this metric with respect to N_{data} ?
- ▶ Understand the observed decay in the absolute slope of the first figure as N_{data} increases?

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